

# Chapter 5

## Least Squares Inverse Eigenvalue Problems

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- Algorithm

## Overview

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- The information of spectral constraint and the structural constraint may not be obtained precisely in practice.
- It may occur in practice that one of the two constraints should be enforced more critically than the other.
  - ◇ Without the physical realizability, the physical system simply cannot be built. So structural constraint is emphasized.
- It may occur that one constraint could be more relaxed than the other.
  - ◇ For complex system there is no accurate way to measure the spectrum or to obtain the entire information. Physical uncertainty can be tolerated up to a certain degree.
- When the two constraints cannot be settled simultaneously, the IEP could be formulated in a least squares setting.

# Formulation

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- All IEP's discussed so far have a natural generalization to least squares formulation.
- Depends upon which constraint is to be enforced, there are two ways to formulate the least squares IEP.

# Least Squares Approximating the Spectrum

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- Given:

- ◇ Symmetric matrices  $A(d) \in \mathbb{R}^{n \times n}$ ,

- ◇ Real numbers  $\lambda_1^*, \dots, \lambda_m^*$ ,

- ◇  $m \leq n$ ,

- Solve:

$$\min_{d \in \mathbb{R}^l, \sigma} F(d, \sigma) = \sum_{i=1}^m (\lambda_{\sigma_i}(d) - \lambda_i^*)^2,$$

$$= \|\Lambda_\sigma(d) - \Lambda_m^*\|_F^2.$$

- ◇  $\sigma :=$  a permutation;

- ◇  $\Lambda_m^* := \text{diag}(\lambda_1^*, \dots, \lambda_m^*)$ .

# Least Squares Approximating the Structure

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- Let

- ◇  $\Lambda_m^* := \text{diag}(\lambda_1^*, \dots, \lambda_m^*)$ .

- ◇  $D_{n-m} := \{\text{diag matrices}\} \subseteq \mathbb{R}^{(n-m) \times (n-m)}$ .

- ◇  $\mathcal{O}(n) := \{\text{orthogonal matrices}\} \subseteq \mathbb{R}^{n \times n}$

- Define:

$$\Gamma := \left\{ Q \begin{bmatrix} \Lambda_m^* & 0 \\ 0 & \Lambda_{n-m} \end{bmatrix} Q^T \mid Q \in \mathcal{O}(n), \Lambda_{n-m} \in D_{n-m} \right\}.$$

- Given:

- ◇ Symmetric matrices  $A(d) \in \mathbb{R}^{n \times n}$ ,

- ◇ Real numbers  $\lambda_1^*, \dots, \lambda_m^*$ ,

- ◇  $m \leq n$ ,

- Solve:

$$\text{dist}(\mathcal{A}(d), \Gamma) = \min_{d \in \mathbb{R}^l, B \in \Gamma} \|A(d) - B\|_F^2.$$

## Main Theorem

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- At a global minimizer, **LSIEP1** and **LSIEP2** are equivalent.

◇ Both problems have the same objective values.

$$\min_{d, \sigma} \|\Lambda_\sigma(d) - \Lambda_m^*\|_F^2 = \min_{d, B} \|A(d) - B\|_F^2.$$

◇ If  $d_1, \sigma$  solve **LSIEP1** and  $d_2, B$  solve **LSIEP2**, then

▷  $d_1 = d_2,$

▷  $B = Q(d_1) \begin{bmatrix} \Lambda_m^* & 0 \\ 0 & \Lambda_{\bar{\sigma}}(d_1) \end{bmatrix} Q(d_1)^T.$

•  $Q(d_1)^T A(d_1) Q(d_1) = \begin{bmatrix} \Lambda_\sigma(d_1) & 0 \\ 0 & \Lambda_{\bar{\sigma}}(d_1) \end{bmatrix}.$

•  $\text{diag}[\Lambda_\sigma(d_1), \Lambda_{\bar{\sigma}}(d_1)]$  has same ordering as  $\text{diag}[\Lambda_m^*, \Lambda_{\bar{\sigma}}(d_1)]$ .

•  $\bar{\sigma} := \{1, \dots, n\} - \sigma.$

◇ If so

$$\min_{d, B} \|A(d) - B\|_F^2 = \sum_{i=0}^m |\lambda_{\sigma_i} - \lambda_i^*|^2.$$

# One Particular Case

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- Consider the special case where

$$A(d) := A_0 + \sum_{i=1}^l d_i A_i \in \mathcal{A}(d) \text{ (affine subspace)}$$

- Lift & Project:

1. Find

$$Z^{(k)} := \arg \min_{B \in \Gamma} \|A(d^{(k)}) - B\|_F \quad \textbf{(Lift)}$$

by the Wielandt-Hoffman Theorem!

2. Find

$$d^{(k+1)} := \arg \min_{d \in \mathbb{R}^l} \|Z^{(k)} - \mathcal{A}(d)\|_F \quad \textbf{(Project)}$$

by solving a linear system.

- The topology of  $\Gamma$  is not clear. But *Step 1* can be accomplished by considering a “substructure”.

$$\mathcal{M}_k := \left\{ Q \begin{bmatrix} \Lambda_m^* & 0 \\ 0 & \Lambda_{\bar{\sigma}}(d^{(k)}) \end{bmatrix} Q^T \mid Q \in \mathcal{O}(n) \right\}$$

which is known.

# Geometric Sketch

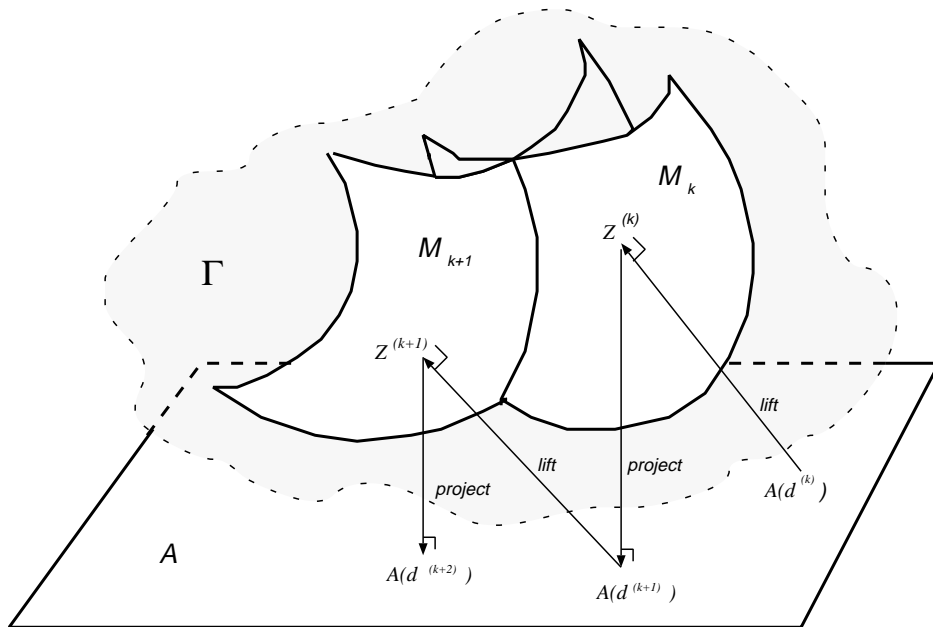


Figure 1: Geometry of lift and projection.

- This a descent method!

$$\begin{aligned} \|Z^{(k+1)} - A(d^{(k+1)})\|_F &\leq \|Z^{(k)} - A(d^{(k+1)})\|_F \\ &\leq \|Z^{(k)} - A(d^{(k)})\|_F \end{aligned}$$



# Algorithm

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- Given  $d^{(0)}$ .
- For  $k = 0, 1, 2, \dots$ 
  1. Compute  $Q(d^{(k)})$  and  $\Lambda(d^{(k)})$ .
  2. Find  $\sigma = \{\sigma_1, \dots, \sigma_m\}$ . Form  $\Lambda_{\bar{\sigma}}$
  3. (**lift**) Form

$$Z^{(k)} = Q(d^{(k)}) \text{diag}(\Lambda^*, \Lambda_{\bar{\sigma}}(d^{(k)})) Q(d^{(k)})^T.$$

4. (**Project**) Compute  $d^{(k+1)}$  from

$$\sum_{i=1}^l \langle A_i, A_j \rangle d_i^{(k+1)} = \langle Z^{(k)} - A_0, A_j \rangle.$$

5. stop if  $\|d^{(k+1)} - d^{(k)}\| < \varepsilon$