

# Inverse Eigenvalue Problems: Theory and Applications

A Series of Lectures to be Presented at IRMA, CNR, Bari, Italy

Moody T. Chu  
(Joint with Gene Golub)

Department of Mathematics  
North Carolina State University

June 27, 2001



# Preface

An inverse eigenvalue problem concerns the reconstruction of a matrix from prescribed spectral data. The spectral data involved may consist of the complete or only partial information of eigenvalues or eigenvectors. The objective of an inverse eigenvalue problem is to construct a matrix that maintains a certain specific structure as well as that given spectral property.

Inverse eigenvalue problems arise in a remarkable variety of applications, including system and control theory, geophysics, molecular spectroscopy, particle physics, structure analysis, and so on. Generally speaking, the basic goal of an inverse eigenvalue problem is to reconstruct the physical parameters of a certain system from the knowledge or desire of its dynamical behavior. Since the dynamical behavior often is governed by the underlying natural frequencies and/or normal modes, the spectral constraints are thus imposed. On the other hand, in order that the resulting model is physically realizable, additional structural constraints must also be imposed upon the matrix. Depending on the application, inverse eigenvalue problems appear in many different forms.

Associated with any inverse eigenvalue problem are two fundamental questions – the theoretic issue on solvability and the practical issue on computability. Solvability concerns obtaining a necessary or a sufficient condition under which an inverse eigenvalue problem has a solution. Computability concerns developing a procedure by which, knowing a priori that the given spectral data are feasible, a matrix can be constructed numerically. Both questions are difficult and challenging.

In this note the emphasis is to provide an overview of the vast scope of this fascinating problem. The fundamental questions, some known results, many applications, mathematical properties, a variety of numerical techniques, as well as several open problems will be discussed.

This research was supported in part by the National Science Foundation under the grants DMS-9803759 and DMS-0073056. The lectures are to be presented at the Istituto per Ricerche di Matematica Applicata (IRMA), Bari, Italy, from June 23 to July 20, 2001, upon the invitation by Fasma Diele. The visit to present this series of lectures is made possible by Professor Roberto Peluso at the IRMA and Professor Dario Bini at the Universita' di Pisa with the support from the Il Consiglio Nazionale delle Ricerche (CNR) and the Gruppo Nazionale per il Calcolo Scientifico (GNCS) of the Istituto Nazionale di Alta Matematica (INDAM) under the project "Algebra Lineare Numerica per Problemi con Struttura e Applicazioni". The warm kindness and encouragement received from these colleagues are greatly appreciated.

Moody T. Chu  
Raleigh, North Carolina

May, 2001

# Contents

<b>Preface</b>	<b>iii</b>
<b>1 Introduction</b>	<b>1</b>
Overview . . . . .	2
Inverse Eigenvalue Problem (IEP) . . . . .	3
Fundamental Questions . . . . .	4
Brief History . . . . .	5
Literature Review . . . . .	6
Applications . . . . .	8
An Example . . . . .	9
Classification . . . . .	11
Via Algebraic Characteristics . . . . .	12
Via Physical Characteristics . . . . .	19
A Glimpse of Some Major Issues . . . . .	20
Complex Solvability . . . . .	21
Real Solvability . . . . .	22
Numerical Methods . . . . .	23
Sensitivity Analysis . . . . .	24
Summary . . . . .	25
<b>2 Applications</b>	<b>27</b>
Pole Assignment Problem . . . . .	28
State Feedback Control . . . . .	29
Output Feedback Control . . . . .	30
Control of Vibration . . . . .	31
Undamped System . . . . .	32
Damped System . . . . .	34
Inverse Sturm-Liouville Problem . . . . .	35
Matrix Analogue . . . . .	36
Applied Physics . . . . .	37
Quantum Mechanics . . . . .	38
Geophysics . . . . .	39
Neutron Transport Theory . . . . .	40

Numerical Analysis . . . . .	42
Preconditioning . . . . .	43
High Order Stable Runge-Kutta Schemes . . . . .	45
Gauss Quadratures . . . . .	47
Low Rank Approximation . . . . .	50
<b>3 Parameterized Inverse Eigenvalue Problems</b>	<b>51</b>
Overview . . . . .	52
Generic Form . . . . .	53
Variations . . . . .	54
General Results . . . . .	55
Existence Theory for Linear PIEP . . . . .	56
Complex Solvability . . . . .	57
Real Solvability ( $n = m$ ) . . . . .	58
Multiple Eigenvalue . . . . .	60
Sensitivity Analysis . . . . .	61
Forward Problem for General $A(c)$ . . . . .	62
Inverse Problem for Linear Symmetric $A(c)$ . . . . .	63
Numerical Methods . . . . .	64
Direct Method . . . . .	65
Iterative Methods . . . . .	66
Continuous Methods . . . . .	74
Additive Inverse Eigenvalue Problems . . . . .	79
Subvariations . . . . .	80
Solvability Issues . . . . .	81
Sensitivity Issues (for AIEP2) . . . . .	83
Numerical Methods . . . . .	84
Newton's Method (for AIEP2) . . . . .	85
Homotopy Method (for AIEP3) . . . . .	86
Multiplicative Inverse Eigenvalue Problems . . . . .	87
Subvariations . . . . .	88
Solvability Issues . . . . .	89
Optimal Conditioning by Diagonal Matrices . . . . .	91
Sensitivity Issues (for MIEP2) . . . . .	92
Numerical Methods . . . . .	93
Reformulate MIEP1 as Nonlinear Equations . . . . .	94
Newton's Method (for MIEP2) . . . . .	95
<b>4 Structured Inverse Eigenvalue Problems</b>	<b>97</b>
Jacobi Inverse Eigenvalue Problems . . . . .	98
Overview . . . . .	99
Subvariations . . . . .	100
Physical Interpretations . . . . .	104

Existence Theory . . . . .	107
Sensitivity Issues . . . . .	110
Numerical Methods . . . . .	111
Lanczos Method (for SIEP6a) . . . . .	112
Orthogonal Reduction Method (for SIEP6a) . . . . .	113
Toeplitz Inverse Eigenvalue Problem . . . . .	115
Overview . . . . .	116
Spectral Properties of Centrosymmetric Matrices . . . . .	117
A $3 \times 3$ Example . . . . .	119
Inverse Problem for Centrosymmetric Matrices . . . . .	121
Existence . . . . .	122
Numerical Methods . . . . .	125
Continuous Method . . . . .	126
Refined Newton to Centrosymmetric Structure . . . . .	127
Numerical Experiment . . . . .	137
Conclusion . . . . .	148
Nonnegative Inverse Eigenvalue Problem . . . . .	149
Overview . . . . .	150
Some Existence Results . . . . .	151
Symmetric Nonnegative Inverse Eigenvalue Problem . . . . .	152
Numerical Method . . . . .	153
Stochastic Inverse Eigenvalue Problem . . . . .	154
General View . . . . .	155
Karpelević's Theorem . . . . .	156
Relation to Nonnegative Matrices . . . . .	158
Basic Formulation . . . . .	159
Steepest Descent Flow . . . . .	162
ASVD flow . . . . .	163
Convergence . . . . .	167
Numerical Experiment . . . . .	168
Conclusion . . . . .	175
Unitary Inverse Eigenvalue Problem . . . . .	177
Overview . . . . .	178
Formulation . . . . .	179
Existence Theory . . . . .	180
Inverse Eigenvalue Problems with Prescribed Entries . . . . .	181
Overview . . . . .	182
Prescribed Entries along the Diagonal . . . . .	183
Schur-Horn Theorem . . . . .	184
Mirsky Theorem . . . . .	185
Sing-Thompson Theorem . . . . .	186
de Oliveira Theorem . . . . .	187
Prescribed Entries at Arbitrary Locations . . . . .	188

Cardinality and Locations . . . . .	189
Numerical Methods . . . . .	191
Inverse Singular Value Problems . . . . .	192
IEP versus ISVP . . . . .	193
Existence Question . . . . .	195
A Continuous Approach . . . . .	197
An Iterative Approach for ISVP . . . . .	202
Inverse Singualar/Eigenvalue Problem . . . . .	225
Overview . . . . .	226
Weyl-Horn Theorem . . . . .	227
A Recursive Algorithm . . . . .	228
The $2 \times 2$ Case . . . . .	229
Ideas in Horn's Proof . . . . .	230
Key to the Algorithmic Success . . . . .	231
Outline of Proof . . . . .	232
A MATLAB Program . . . . .	235
Matrix Structure . . . . .	236
Correct the "Mistake" . . . . .	237
A Variation of Horn's Proof . . . . .	239
A Symbolic Example . . . . .	240
Numerical Experiment . . . . .	242
Rosser Test . . . . .	243
Wilkinson Test . . . . .	245
Conclusion . . . . .	246
<b>5 Least Squares Inverse Eigenvalue Problems</b>	<b>249</b>
Overview . . . . .	250
Formulation . . . . .	251
Least Squares Approximating the Spectrum . . . . .	252
Least Squares Approximating the Structure . . . . .	253
Main Theorem . . . . .	254
One Particular Case . . . . .	255
Geometric Sketch . . . . .	256
Algorithm . . . . .	257
<b>6 Partially Described Inverse Eigenvalue Problems</b>	<b>259</b>
Overview . . . . .	260
Generic Form . . . . .	261
PDIEP for Toeplitz Matrices . . . . .	262

<b>7 Spectrally Constrained Approximation</b>	<b>265</b>
Overview . . . . .	266
Spectrally Constrained Problem . . . . .	267
Singular-Value Constrained Problem . . . . .	268
Reformulation . . . . .	269
Feasible Set $O(n)$ & Gradient of $F$ . . . . .	270
The Projected Gradient . . . . .	271
An Isospectral Descent Flow . . . . .	272
The Second Order Derivative . . . . .	273
Least Squares Approximation . . . . .	274
Sorting Property . . . . .	275
Wielandt-Hoffman Theorem . . . . .	276
Toeplitz Inverse Eigenvalue Problem . . . . .	277
Toeplitz Annihilator . . . . .	278
Eigenvalue Computation . . . . .	280
Simultaneous Reduction . . . . .	281
<b>8 Structured Low Rank Approximation</b>	<b>283</b>
Overview . . . . .	284
Difficulties . . . . .	285
An Example of Existence . . . . .	286
Another Hidden Catch . . . . .	288
Low Rank Toeplitz Approximation . . . . .	289
A General Remark . . . . .	290
Algebraic Structure . . . . .	291
Constructing Lower Rank Toeplitz Matrices . . . . .	294
Lift and Project Algorithm . . . . .	295
Implicit Optimization . . . . .	299
Numerical Experiment . . . . .	300
Explicit Optimization . . . . .	302
An Illustration . . . . .	303
Using Existing Optimization Codes . . . . .	305
Conclusions . . . . .	308
Low Rank Circulant Approximation . . . . .	309
Basic Properties . . . . .	310
Elementary Spectral Properties . . . . .	311
(Inverse) Eigenvalue Problem . . . . .	313
Conjugate Evenness . . . . .	314
Low Rank Approximation . . . . .	315
Trivial $O(n \log n)$ TSVD Algorithm . . . . .	316
Data Matching Problem . . . . .	317
An Example using a Tree Structure . . . . .	319
Numerical Experiment . . . . .	322

Example 1: Symmetric Illustration . . . . .	323
Example 2: Complex Illustration . . . . .	324
Example 3: Perturbed Case . . . . .	325
Conclusion . . . . .	326
Lor Rank Covariance Approximation . . . . .	329
Euclidian Distance Matrix Approximation . . . . .	330
Approximate GCD . . . . .	331