Multivariate Eigenvalue Problem: Algebraic Theory and Power Method

Moody T. Chu and J. Loren Watterson

Department of Mathematics North Carolina State University Raleigh, NC 27695-8205

Outline

- Statistics Background
- Homotopy Method and Cardinality
- Power Method and Convergence
- Other Numerical Methods

Multivariate Eigenvalue Problem (MEP)

Find real scalars $\lambda_1, \ldots, \lambda_m$ and a real vector $x \in \mathbb{R}^n$ such that

$$Ax = \Lambda x$$

$$||x_i|| = 1, \ i = 1, \dots, m,$$

where

• $A \in \mathbb{R}^{n \times n}$ is SPD, and is block partitioned into

$$A = \begin{bmatrix} A_{11} & A_{12} & \dots & A_{1m} \\ A_{21} & A_{22} & \dots & A_{2m} \\ \vdots & \vdots & & \vdots \\ A_{m1} & A_{m2} & \dots & A_{mm} \end{bmatrix},$$

$$Q_{n_i \times n_i}$$

$$-A_{ii} \in R^{n_i \times n_i}.$$

$$-\Sigma_{i=1}^m n_i = n.$$

• $\Lambda = \text{diag}\{\lambda_1 I^{[n_1]}, \dots, \lambda_m I^{[n_m]}\},$

$$-I^{[n_i]}:=\text{The identity matrix of dimension } n_i.$$

• $x = [x_1^T, \dots, x_m^T]^T,$

$$-x_i \in R^{n_i}.$$

Relation to Other Problems

- MEP is a classical symmetric eigenvalue problem when m = 1.
- MEP is fundamentally different from the so called multiparameter eigenvalue problem.
- MEP originates from the determination of canonical correlation coefficients for multivariate statistics.

Statistics Background

- $\tilde{X} := (\mathcal{X}_1, \ldots, \mathcal{X}_n)$ denotes an *n*-dimensional random variable with a certain distribution function.
- Row vectors $[x_{\xi 1}, \ldots, x_{\xi n}], \xi = 1, \ldots, k$ denote a random sample of size k for \tilde{X} ,
 - $-X := [x_{\xi i}]$ is the $k \times n$ sample matrix.
- Assume
 - Sample mean $\mu_i = 0$ for each \mathcal{X}_i .
 - No degenerate component and no linear dependence among \mathcal{X}_i .

Then

- Matrix $\Delta := X^T X$ represents the covariance matrix of the random sample X.
- $-\Delta$ is SPD.

Regroup of Variables

- Divide variables into groups $\tilde{X} = (\tilde{X}_1, \dots, \tilde{X}_m),$
 - $-\tilde{X}_i$ is an n_i -dimensional random variable.
 - Correspondingly, $\Delta = [\Delta_{ij}]$ and $X = [X_1, \ldots, X_m]$.
 - $-\Delta_{ii}$ is the covariance matrix of the $k \times n_i$ sample block X_i .
- Combining all n_i variables in \tilde{X}_i linearly into a single new variable \mathcal{Z}_i through coefficients $b_i \in \mathbb{R}^{n_i}$,
 - Sample matrix X is transformed into $Z := XB := [Z_1, \ldots, Z_m]$ where

$$B := \begin{bmatrix} b_1 & 0 & \dots & 0 \\ 0 & b_2 & & 0 \\ \vdots & & \ddots & \vdots \\ 0 & & \dots & b_m \end{bmatrix}$$

- Covariance matrix corresponding to Z is given by

$$\Omega := Z^T Z = B^T \Delta B.$$

An Example (m = 2)

- Desire to use \mathcal{Z}_1 to predict \mathcal{Z}_2 ,
 - Need to find b_1 and b_2 so that the correlation coefficient between Z_1 and Z_2 is as large as possible.
- Covariance matrix of Z is

$$\Omega = \begin{bmatrix} b_1^T \Delta_{11} b_1 & b_1^T \Delta_{12} b_2 \\ b_2^T \Delta_{21} b_1 & b_2^T \Delta_{11} b_2 \end{bmatrix}.$$

 \bullet Correlation coefficient ρ to be maximized is

$$\rho = \frac{b_1^T \Delta_{12} b_2}{\sqrt{b_1^T \Delta_{11} b_1} \sqrt{b_2^T \Delta_{11} b_2}}.$$

• Normalize the variances of Z_1 and Z_2 to unity. The maximal correlation problem (MCP) becomes

Maximize
$$b^T \Delta b$$

Subject to $b_i^T \Delta_{ii} b_i = 1$, for $i = 1, 2$
where $b := [b_1^T, b_2^T]^T$.

7

Change MCP to MEP

- Each Δ_{ii} is SPD, so the Cholesky decomposition $\Delta_{ii} = T_i^T T_i$ exists.
- Define

$$T := \text{diag}\{T_1, T_2\} x := Tb := [x_1^T, x_2^T]^T, A := T^{-T} \Delta T^{-1}.$$

MCP is transformed into

Maximize
$$x^T A x$$

Subject to $x_i^T x_i = 1, i = 1, 2.$

• MEP follows from differentiating the Lagrangian function

$$\phi(x,\lambda_1,\lambda_2) := x^T A x - \sum_{i=1}^2 \lambda_i (x_i^T x_i - 1)$$

with λ_1 and λ_2 as the Lagrange multipliers.

Maximal Correlation When m > 2

- Heuristic observation:
 - The closer to orthogonality any two sample vectors Z_i, Z_j are, the closer to zero the correlation coefficients will be.
 - The more *similar* the vectors Z_1, \ldots, Z_m are to each other, the more closely the correlation coefficients will approach unity.
- MCP requires the sum of all off-diagonal elements of Ω be maximized subject to the condition that the diagonal elements of Ω be unity.
- Same procedure as fo m = 2 to leads MCP to

Maximize $x^T A x$ Subject to $x_i^T x_i = 1, \ i = 1, m,$

and, then, to MEP.

What Are the Difficulties?

- MEP represents a non-linear algebraic system in n + m unknowns.
- When m = 1,
 - Counting multiplicity, there are exactly n eigenvalues.
 - Counting negative signs, there are exactly 2n eigenvectors.
- When m > 1, no discussion on the cardinality of solutions to MEP,
 - Characteristic polynomial is not applicable to MEP.
- How to compute a multivariate eigenvalue and the corresponding eigenvector?
 - Horst proposed an iterative procedure without a proof.
 - Not heard of any other numerical method since Horst

Homotopy Method and Cardinality

• MEP is a nonlinear system:

$$F(x,\Lambda) := \begin{bmatrix} \Lambda x - Ax \\ \frac{x_1^T x_1 - 1}{2} \\ \vdots \\ \frac{x_m^T x_m - 1}{2} \end{bmatrix} = 0,$$

 $-F: R^n \times R^m \longrightarrow R^n \times R^m.$

• The simple MEP:

$$Dx = \Lambda x$$

$$||x_i|| = 1, \ i = 1, \dots, m.$$

with $D = \text{diag}\{d_1^{(1)}, \dots, d_{n_1}^{(1)}, \dots, d_1^{(m)}, \dots, d_{n_m}^{(m)}\}$ has exactly $\prod_{i=1}^m 2n_i$ solutions,

- For i = 1, ..., m,

$$\lambda_i = d_{j_i}^{(i)},$$

$$x_i = \pm e_{j_i}^{[n_i]},$$

* $j_i = 1, \ldots, n_i$. * $e_s^{[t]} := s^{th}$ column of $I^{[t]}$.

Homotopy Function

- Define $H: R^n \times R^m \times R \longrightarrow R^n \times R^m$ by $H(x, \Lambda, t; D) := \begin{bmatrix} \Lambda x - [D + t(A - D)]x \\ \frac{x_1^T x_1 - 1}{2} \\ \vdots \\ \frac{x_m^T x_m - 1}{2} \end{bmatrix},$
 - $-\ D$ is a diagonal matrix whose elements will be specified.
- Basic Ideas:
 - The set $\Gamma := \{(x, \Lambda, t) | H(x, \Lambda, t) = 0\}$ is a one dimensional smooth submanifold in $\mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}$.
 - No homotopy curve will escape to infinity or turn back.

Major Theorem

For each $(x, \Lambda, t) \in \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}$ such that $H(x, \Lambda, t) = 0$, the matrix

$$D_{(x,\Lambda)}H = \begin{bmatrix} \mathcal{A} & \mathcal{B} \\ \mathcal{B}^T & 0 \end{bmatrix}$$

where

$$\mathcal{A} = \mathcal{A}(\Lambda, t, D) := \Lambda - (D + t(A - D)).$$

and

$$\mathcal{B} := \begin{bmatrix} x_1 & 0 & \dots & 0 \\ 0 & x_2 & \dots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & & \dots & x_m \end{bmatrix}$$

has rank n + m.

- If $H(x, \Lambda, t) = 0$, then $\mathcal{A}x = 0$.
- None of the m columns of \mathcal{B} can be in the range of \mathcal{A} .
- \mathcal{A} is at least of rank n-m.

Auxiliary Lemma

The set of D such that the matrix $\Lambda - (D + t(A - D))$ is of rank less than n - m for some Λ and some $t \in (0, 1)$ is of measure zero.

• If the rank of \mathcal{A} is less than n - m, then one of the diagonal blocks

$$\mathcal{A}_{ii} = \lambda_i I^{[n_i]} - (1-t) \operatorname{diag}(d_1^{(i)}, \dots, d_{n_i}^{(i)}) - t A_{ii}$$

must be rank deficient by at least two.

- For some $\tau \in (0, \infty)$ the matrix $\tau D^{(i)} + A_{ii}$ has an eigenvalue with multiplicity at least two, $-D^{(i)} := \operatorname{diag}(d_1^{(i)}, \ldots, d_{n_i}^{(i)}).$
- For any symmetric matrix M, the set

 $E_r := \{ \text{diagonal } D | M + D \text{ rank deficient by } r \}$

has dimension $\leq \dim(M) - 3$ for $r \geq 2$.

• The set

 $\bigcup_{\tau \in (0,\infty)} \{ D^{(i)} | \tau D^{(i)} + A_{ii} \text{ has multiple eigenvalues} \}$

is of dimension at most $n_i - 1$.

Homotopy Curves

For $i = 1, \ldots, m$, the solution to the initial value problem

$$\frac{d}{dt} \begin{bmatrix} x_1 \\ \vdots \\ x_m \\ \lambda_1 \\ \vdots \\ \lambda_m \end{bmatrix} = \begin{bmatrix} \mathcal{A} & \mathcal{B} \\ \mathcal{B}^T & 0 \end{bmatrix}^{-1} \begin{bmatrix} -\mathcal{C} \\ 0 \end{bmatrix}$$

$$x_i(0) = \pm e_{j_i}^{[n_i]}$$

$$\lambda_i(0) = d_{j_i}^{(i)}$$

is a curve in $\mathbb{R}^n \times \mathbb{R}^m$ that extends from t = 0 to t = 1.

- The (MEP) has exactly $\prod_{i=1}^{m} 2n_i$ solutions.
- The positive definiteness of the matrix A is not needed in the proof.

Horst's Algorithm

• Block form: Given $x^{(0)} = (x_1^{(0)^T}, \dots, x_m^{(0)^T})^T$ with $||x_i^{(0)}|| = 1$, do for $k = 1, 2, \dots$ for $i = 1, \dots, m$ $y_i^{(k)} := \sum_{j=1}^m A_{ij} x_j^{(k)},$ $\lambda_i^{(k)} := ||y_i^{(k)}||,$ $x_i^{(k+1)} := \frac{y_i^{(k)}}{\lambda_i^{(k)}}.$

end

end

- Define $x_i^{(k+1)} := x_i^{(k)}$ in case $||y_i^{(k)}|| = 0$.

• Compact form:

$$Ax^{(k)} = \Lambda^{(k)} x^{(k+1)},$$

- $x^{(k)} := [x_1^{(k)^T}, \dots, x_m^{(k)^T}]^T$
- $\Lambda^{(k)} := \text{diag}\{\lambda_1^{(k)} I^{[n_1]}, \dots, \lambda_m^{(k)} I^{[n_m]}\}.$

Is This a Power Method?

- Horst's iteration may be viewed as a generalization of the classical power method.
- The convergence property of this method is not nearly obvious,
 - Without the positive definiteness, the method may fail to converge.
 - A limit point of the method may depend upon the starting point.
 - MCP may have multiple local solutions.

Convergence!

• The sequence $\{r(x^{(k)})\}$ where $r(x) := x^T A x.$

is a monotonically increasing sequence and converges. – Key fact,

$$r(x^{(k+1)}) - r(x^{(k)}) = (x^{(k+1)} - x^{(k)})^T (A + \Lambda^{(k)}) (x^{(k+1)} - x^{(k)}).$$

• The residual $\{\delta x^{(k)}\}$ where

$$\delta(x) := Ax - \Lambda x$$

converges to zero.

- Key fact,

$$\delta(x^{(k)}) = \Lambda^{(k)} (x^{(k+1)} - x^{(k)}).$$

Convergence?

• Is this enough to prove convergence of $\{x^{(k)}\}$?

$$r(x^{(k+1)}) - r(x^{(k)}) \ge \kappa ||x^{(k+1)} - x^{(k)}||^2$$

- The sequence $\{x^{(k)}\}$ does have have cluster point(s),
 - Every cluster point x^* solves MEP with eigenvalues $\lambda_i^* := || \sum_{j=1}^m A_{ij} x_j^* ||.$
- A lemma from real analysis,
 - Let $\{a_k\}$ be a bounded sequence of real numbers with the proper $|a_{k+1} - a_k| \longrightarrow 0$ as $k \longrightarrow \infty$. If there are only finitely many limit points for the sequence, then $\{a_k\}$ converges to a unique limit point.
- The fact of finite number of solutions of MEP proves that
 - The sequence $\{\Lambda^{(k)}\}$ converges.
 - The sequence $\{x^{(k)}\}$ converges.

Dependence on Starting Points

Consider the positive definite matrix

$$A = \begin{bmatrix} 4.3299 & 2.3230 & -1.3711 & -0.0084 & -0.7414 \\ 2.3230 & 3.1181 & 1.0959 & 0.1285 & 0.0727 \\ -1.3711 & 1.0959 & 6.4920 & -1.9883 & -0.1878 \\ -0.0084 & 0.1285 & -1.9883 & 2.4591 & 1.8463 \\ -0.7414 & 0.0727 & -0.1878 & 1.8463 & 5.8875 \end{bmatrix}$$

with m = 2, $n_1 = 2$ and $n_2 = 3$. • If $x^{(0)} = [0.9777, 0.2098, 0.5066, 0.5069, 0.6975]^T$, then

$$x^* = [0.9357, 0.3528, -0.9341, 0.3508, 0.0667]^T,$$

$$\lambda_1^* = 6.5186,$$

$$\lambda_2^* = 8.2116.$$

• If $x^{(0)} = [0.7914, 0.6114, 0.4753, 0.2517, -0.8431]^T$, then $x^{**} = [0.7166, 0.6975, 0.5654, -0.4327, -0.7022]^T,$ $\lambda_1^{**} = 6.2405,$ $\lambda_2^{**} = 7.8607.$

Random Test

- Approximately 60% randomly generated starting points converge to x^* while all the remaining converge to x^{**} ,
 - Out of the 24 solutions, there are two local maxima to the maximal correlation problem.
 - Horst's algorithm has a substantial possibility of not converging to the absolute maximal correlation.

Multivariate Shifting

- $(A \Gamma)x = \Lambda x$ if and only if $Ax = (\Gamma + \Lambda)x$,
 - Shifting is a possible strategy to find other solution of MEP.
- How do limit points depend on the starting value and on the shift parameters?
- For what Γ will the matrix $A \Gamma$ become positive semidefinite?

Gauss-Seidel Algorithm

• Block form: Given $x^{(0)} = (x_1^{(0)^T}, \dots, x_m^{(0)^T})^T$ with $||x_i^{(0)}|| = 1$, do for $k = 1, 2, \dots$ for $i = 1, \dots, m$ $y_i^{(k)} := \sum_{j=1}^{i-1} A_{ij} x_j^{(k+1)} + \sum_{j=i}^m A_{ij} x_j^{(k)}$ $\lambda_i^{(k)} := ||y_i^{(k)}||,$ $x_i^{(k+1)} := \frac{y_i^{(k)}}{\lambda_i^{(k)}}.$

end

end

• Compact form:

$$(D+U)x^{(k)} = (\Lambda^{(k)} - U^T)x^{(k+1)},$$

 $-A = D + U^T + U.$

• Block form: Given $x^{(0)} = (x_1^{(0)^T}, \dots, x_m^{(0)^T})^T$ with $||x_i^{(0)}|| = 1$, do for $k = 1, 2, \dots$ for $i = 1, \dots, m$ $\overline{y}_i^{(k)} := \sum_{j=1}^{i-1} A_{ij} x_j^{(k+1)} + \sum_{j=i}^m A_{ij} x_j^{(k)}$ $\xi_i^{(k)} := ||\overline{y}_i^{(k)}||,$ $\overline{z}_i^{(k+1)} := \frac{\overline{y}_i^{(k)}}{\xi_i^{(k)}}.$ $y_i^{(k)} := \omega_i \overline{z}_i^{(k+1)} + (1 - \omega_i) x_i^{(k)}$ $\lambda_i^{(k)} := ||y_i^{(k)}||,$ $x_i^{(k+1)} := \frac{y_i^{(k)}}{\lambda_i^{(k)}}.$

end

end

- Relaxation parameters ω_i may be different.
- The scaling may be done differently.
- Compact form:

$$[(I - \Omega)\Xi^{(k)} + \Omega(D + U)]x^{(k)} = (\Xi^{(k)}\Lambda^{(k)} - \Omega U^T)x^{(k+1)}, - \Xi^{(k)} := \operatorname{diag}\{\xi_1^{(k)}I^{[n_1]}, \dots, \xi_m^{(k)}I^{[n_m]}\}. - \Omega := \operatorname{diag}\{\omega_1 I^{[n_1]}, \dots, \omega_m I^{[n_m]}\}.$$

Future Research

- A partial list of problems includes
 - Proof of convergence,
 - This can be done.
 - Rate of convergence.
 - Acceleration of convergence.